

# Presymplectic structures and intrinsic Lagrangians

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Based on:

*M.G., to appear*

*M.G., A. Verbovetsky, to appear*

*K. Alkalaev, M.G. 2013*

Also:

*M.G. 2012*

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## Motivations

- Lagrangians (or their substitutes) are inevitable for quantization
- Existence of a Lagrangian formulation is often considered as a selection criterium
- Analysis becomes problematic once auxiliary fields are in the game.  
Ex.: unfolded formulation of HS theories etc.
- Lack of an invariant understanding of the structures underlying Lagrangian formulation

# Jet space

Space-time coordinates (independent variables):  $x^a$ ,  $a = 1, \dots, n$ .

Fields (dependent variable)  $\phi^i$ .

$$J^0 : x^a, \phi^i, \quad J^1 : x^a, \phi^i, \phi_a^i, \quad J^2 : x^a, \phi^i, \phi_a^i, \phi_{ab}^i, \quad \dots$$

Projections:

$$\dots \rightarrow J^N \rightarrow J^{N-1} \rightarrow J^{N-2} \rightarrow \dots \rightarrow J^1 \rightarrow J^0$$

Useful to work with  $J^\infty$ . A **local** diff. form on  $J^\infty$  – a form on  $J^N$  for some  $N$  seen as that on  $J^\infty$ .

$J^\infty$  is equipped with the total derivative

$$\partial_a^T = \frac{\partial}{\partial x^a} + \phi_a^i \frac{\partial}{\partial \phi^i} + \phi_{ab}^i \frac{\partial}{\partial \phi_b^i} + \dots$$

For a given field configuration  $\phi^i = s^i(x)$  and local function  $f[\phi]$

$$\left( \partial_a^T f \right) \Big|_{\phi=s, \phi_a=\partial_a s, \dots} = \partial_a \left( f \Big|_{\phi=s, \phi_a=\partial_a s, \phi_{ab}=\partial_a \partial_b s, \dots} \right)$$

Space time differentials  $dx^a$ . Horizontal differential

$$Q \equiv d_H = dx^a \partial_a^T, \quad Q^2 = 0.$$

Differential forms:

$$\alpha = \alpha(x, dx, \phi, \phi_a, \dots)_{I_1 \dots I_k} d_V \phi^{I_1} \dots d_V \phi^{I_k}, \quad \phi^I = \phi_{a_1 \dots a_m}^i$$

Vertical De Rham differential:

$$d_V = d - Q = d_V \phi^I \frac{\partial}{\partial \phi^I}$$

Variational bicomplex:

$$d_V^2 = 0, \quad d_V Q + Q d_V = 0, \quad Q^2 = 0$$

Bidegree  $(l, p)$ .

A system of partially differential equations (PDE) is a collection of local functions

$$E_\alpha[\phi, x].$$

The equation manifold (stationary surface) is  $\mathcal{E} \subset J^\infty$  singled out by:

$$\partial_{a_1}^T \dots \partial_{a_l}^T E_\alpha = 0, \quad l = 0, 1, 2, \dots$$

understood as the algebraic equations in  $J^\infty$ . It is usually assumed that  $x^a, \phi^i$  are not constrained, e.g.  $\mathcal{E}$  is a bundle over the space-time.

$\partial_a^T$  are tangent to  $\mathcal{E}$  and hence restricts to  $\mathcal{E}$ . So do the differentials  $Q$  and  $d_V$ .  $\partial_a^T|_{\mathcal{E}}$  determine a  $\dim-n$  integrable distribution (Cartan distribution).

*Definition: [Vinogradov] A PDE is a manifold  $\mathcal{E}$  equipped with an integrable distribution.*

In addition one typically assumes regularity, constant rank, and that  $\mathcal{E}$  is a bundle over the spacetime. Use notation  $(\mathcal{E}, Q)$ .

In this form it is clear which PDEs are to be considered isomorphic.

**Scalar field Example:** Start with:

$$L = \frac{1}{2} \eta^{ab} \phi_a \phi_b - V(\phi)$$

$\mathcal{E}$  is coordinatized by  $x^a, \phi, \phi_a, \phi_{ab}, \dots$ . Already  $\phi_{ab}$  are not independent.

One can e.g. take  $\phi_{abc\dots}$  traceless. The  $Q$  differential on  $\mathcal{E}$  reads as

$$Qx^a = dx^a, \quad Q\phi = dx^a \phi_a, \quad Q\phi_a = dx^b \left( \phi_{ab} - \frac{1}{n} \eta_{ab} \frac{\partial V}{\partial \phi} \right), \quad \dots$$

So if the system is nonlinear, i.e.  $\frac{\partial V}{\partial \phi}$  nonlinear in  $\phi$ ,  $Q$  is also nonlinear.

## Intrinsic (unfolded) realization

Given PDE  $(\mathcal{E}, Q)$  defined invariantly one can always find a jet space  $\mathcal{J}$  such that  $(\mathcal{E}, Q)$  can be realized as a stationary surface of some  $E_\alpha[u, x]$ .

There is an intrinsic way to realize  $(\mathcal{E}, Q)$  explicitly. If  $x^a, \psi^A$  coordinates on  $\mathcal{E}$  (e.g.  $\psi^A = \{\phi, \phi_a, \phi_{ab}, \dots\}$ ) promote  $\psi^A$  to fields  $\psi^A(x)$  of a new theory and subject them to EOM's

$$d\psi^A = Q\psi^A, \quad \text{components: } \frac{\partial}{\partial x^a} \psi^A(x) = (\partial_a^T \psi^A)(x)$$

**Proposition:** *The original PDE  $(\mathcal{E}, Q)$  is equivalent to  $d\psi^A = Q\psi^A$*

Comments:

- Version of the unfolded formulation (though only zero forms). Unfolded form of gauge systems involves gauge form-fields. *Vasiliev, 1987,...*
- Generalized version of the Proposition involving gauge forms and BRST extension was formulated and proved using BRST technique and Koszul-Tate differential. *Barnich, M.G., Semikhatov, Tipunin 2004, Barnich, M.G 2010*

## Jet space formulation

Because  $\mathcal{E}$  is a bundle over spacetime, take  $\mathcal{J}^{new} = J^\infty(\mathcal{E})$ . More precisely, if  $x^a, dx^a, \psi^A$  are coordinates on  $\mathcal{E}$  then

$$x^a, dx^a, \psi^A, \psi_b^A, \psi_{bc}^A, \psi_{bcd}^A, \dots$$

are coordinates on  $\mathcal{J}^{new}$ .

New jet space is equipped with its own horizontal differential:

$$D_H = dx^a \left( \frac{\partial}{\partial x^a} + \psi_a^A \frac{\partial}{\partial \psi^A} + \psi_{ab}^A \frac{\partial}{\partial \psi_b^A} + \dots \right)$$

“Old” differential  $Q$  on  $\mathcal{E}$  is extended to  $\mathcal{J}^{new}$  by  $[D_H, Q] = 0$ .

In the new jet space  $\mathcal{J}^{new}$  consider the following PDE

$$D_H \psi^A = Q \psi^A$$

In this form the new PDE is manifestly isomorphic to  $(\mathcal{E}, Q)$  (because manifolds are isomorphic and horizontal differentials are equal by construction)



## Variational (Lagrangian) equations

Let us get back to equations  $E_i[\phi, x] = 0$  on the jet space  $J^\infty$ . These are said variational (Lagrangian) if

$$\mathcal{E}_i = \frac{\delta^{EL} L}{\delta \phi^i}, \quad \frac{\delta^{EL} F[u, x]}{\delta \phi^i} \equiv \frac{\partial F}{\partial \phi^i} - \partial_a^T \frac{\partial F}{\partial \phi_a^i} + \partial_a^T \partial_b^T \frac{\partial F}{\partial \phi_{ab}^i} - \dots$$

for some local function  $L = L[\phi, x]$ . It is convenient to work in terms of Lagrangian density  $\mathcal{L} = (dx)^n L$ .

Here and below

$$(dx)^n = dx^1 \dots dx^n, \quad (dx)_a^{n-1} = \frac{1}{(n-1)!} \epsilon_{ab_2 \dots b_n} dx^{b_1} \dots dx^{b_n}$$

The notion of Lagrangian is explicitly based on the realization of the equation  $(\mathcal{E}, Q)$  in terms of the jet space  $\mathcal{J}$ . For instance it's possible that  $\mathcal{E} \subset \mathcal{J}$  is variational while  $\mathcal{E} \subset \mathcal{J}'$  is not. Naive invariant object – the restriction of  $\mathcal{L}$  to  $\mathcal{E}$ , does not make much sense.

## Presymplectic structure

It is well-known that  $\mathcal{L} = (dx)^n L[x, \phi]$  induce an invariant object on  $\mathcal{E}$

*Crnkovic, Witten, 1987, Hydon 2005,...*

$$(dx)^n E_i d\phi^i = d_V \mathcal{L} - Q \hat{\chi}, \quad \text{components: } \frac{\delta^{EL} L}{\delta \phi^i} = \frac{\partial L}{\partial \phi^i} + \partial_a^T (\hat{\chi}_i^a)$$

for some 1 form  $\hat{\chi} = \hat{\chi}_i d_V \phi^i + \hat{\chi}_{ia} d_V \phi_a^i + \dots$  of degree  $n - 1$ , called presymplectic potential. For  $\chi = \hat{\chi}|_{\mathcal{E}}$  we have

$$Q\sigma = 0, \quad \sigma = d\chi$$

So we have conserved closed 2-form on  $\mathcal{E}$ . It's called **canonical presymplectic structure**.

As an example consider  $L(\phi, \phi_a, \phi_{ab})$ . One finds:

$$\chi = (dx)_a^{n-1} \left( \left( \frac{\partial L}{\partial \phi^a} - \partial_b^T \frac{\partial L}{\partial \phi_{ab}} \right) d_V \phi + \frac{\partial L}{\partial \phi_{ab}} d_V \phi_b \right) \Big|_{\mathcal{E}}$$

In particular, for a scalar field with  $L = \frac{1}{2} \eta^{ab} \phi_a \phi_b - V(\phi)$

$$\chi = (dx)_a^{n-1} \phi^a d_V \phi, \quad \sigma = (dx)_a^{n-1} d_V \phi^a d_V \phi$$

More generally:

*Definition: A 2-form  $\sigma$  of degree  $n - 1$  on  $(\mathcal{E}, Q)$  is called compatible presymplectic structure if  $Q\sigma = 0, d\sigma = 0$ .*

Such form in general can be considered irrespective of any realization in terms of jet space and/or Lagrangian.

## Symmetries and conservation laws

A well-known fact: both symmetries and conservation laws can be defined in terms of the equation manifold  $(\mathcal{E}, Q)$ .

Recall: a vector field  $\hat{V}$  on  $\mathcal{J}$  is a symmetry if it is evolutionary i.e.  $[Q, \hat{V}] = 0$  and tangent to  $\mathcal{E} \subset \mathcal{J}$ .

Intrinsic terms: a vector field  $V$  on  $(\mathcal{E}, Q)$  satisfying is called **symmetry** if  $[Q, V] = 0$  (typically one also requires  $Vx^a = 0$ ).

If  $\mathcal{E} \subset \mathcal{J}$  is variational then variational symmetries restricted to  $\mathcal{E}$  satisfy in addition

$$L_V \sigma = 0$$

Conservation law (conserved current) is a degree  $n - 1$  0-form  $K$  on  $\mathcal{E}$  such that  $QK = 0$ .  $K$  of the form  $K = QM$  is trivial.

Any compatible presymplectic structure determines a map from symmetries to conserved currents according to

$$dK = i_V \sigma, \quad \text{components: } \frac{\partial}{\partial \psi^A} K = \sigma_{AB} V^B$$

Note:  $di_V \sigma = L_V \sigma = 0$ . Trivial symmetries are mapped to trivial conserved currents. In the Lagrangian case this is Noether theorem. General case was also discussed recently *Sharapov 2016.*

Note that it is different from the Poisson (BV antibracket) bracket map from conservation laws to symmetries. The degenerate version of the bracket is known as Lagrange structure *Lyakhovich, Sharapov*

Suppose that  $(\mathcal{E}, Q, \sigma)$  is realized as  $\mathcal{E} \subset J^\infty$ . Then  $\sigma$  determines a Lagrangian form  $\mathcal{L}$  on  $J^\infty$  such that EL equations derived from  $\mathcal{L}$  are in general consequences of those defining  $\mathcal{E}$ .

More precisely, if  $\mathcal{E}'$  is an equation manifold defined by  $\mathcal{L}$  then  $\mathcal{E} \subset \mathcal{E}'$ . Even if  $\sigma$  is canonical (derived from a Lagrangian) there is no guarantee that constructed  $\mathcal{L}$  is equivalent to the starting point Lagrangian.

*Khavkine 2012, based on earlier: Bridges, Hydon, Lawson 2009, Hydon 2005*

## Intrinsic Lagrangian

Given an equation manifold  $(\mathcal{E}, Q, \sigma)$  equipped with the compatible presymplectic structure one can construct a **natural** Lagrangian in terms of the  $\mathcal{E}$ -valued fields.

First: define generalized Hamiltonian (better BRST charge) which is a conserved current associated to  $Q$  seen as a symmetry of  $\mathcal{E}$ . Degree  $n$  function  $\mathcal{H}$  on  $\mathcal{E}$  defined by

$$d_V \mathcal{H} = i_Q \sigma, \quad \text{components: } \frac{\partial}{\partial \psi^A} \mathcal{H} = \sigma_{AB} Q^B$$

In the Lagrangian case

$$\mathcal{H} = \chi_A Q^A - \mathcal{L}|_{\mathcal{E}} \quad Q^A = Q \psi^A$$

E.g. in the simple case where  $\mathcal{L} = (dx)^n L(\phi, \phi_a)$

$$\chi = (dx)_a^{n-1} \left( \frac{\partial L}{\partial \phi_a} d_V \phi \right) \Big|_{\mathcal{E}}, \quad \mathcal{H} = (dx)^n \left( \frac{\partial L}{\partial \phi_a} \phi_a - L \right) \Big|_{\mathcal{E}}$$

New (intrinsic) Lagrangian:

$$\mathcal{L}^C = i_d \chi - \mathcal{H}, \quad \text{components: } \mathcal{L}^C = \chi_A d\psi^A - \mathcal{H}$$

The respective action can be seen as presymplectic generalization

*Alkalaev, M.G. 2013*

$$S^C = \int \left( \chi_A(\psi, x, dx) d\psi^A(x) - \mathcal{H}(\psi, x, dx) \right)$$

of AKSZ action. Its equations of motion read as

$$\sigma_{AB}(d\psi^B - Q^B) = 0,$$

and hence are consequences of the original  $d\psi^B - Q^B = 0$ .

For a local theory  $\mathcal{L}^C$  does not depend on most of the fields  $\psi^A$ . These can be treated as pure-gauge variables with algebraic (shift) gauge transformations. With this interpretation and under certain assumptions we can prove that starting point  $\mathcal{L}$  and  $\mathcal{L}^C$  are equivalent.



## Examples

**Scalar field:** Start with:

$$L = \frac{1}{2}\eta^{ab}\phi_a\phi_b - V(\phi) \quad (1)$$

$\mathcal{E}$  is coordinatized by  $x^a, \phi, \phi_a, \phi_{ab}, \dots$  take  $\phi_{abc\dots}$  traceless. The  $Q$  differential reads as

$$Qx^a = dx^a, \quad Q\phi = dx^a\phi_a, \quad Q\phi_a = dx^b(\phi_{ab} - \frac{1}{n}\eta_{ab}\frac{\partial V}{\partial\phi})$$

The presymplectic potential and 2-form:

$$\chi = \left( (dx)_a^{n-1} \left( \frac{\partial L}{\partial\phi^a} - \partial_c^T \frac{\partial L}{\partial\phi_{ca}} \right) d_V\phi \right) \Big|_{\mathcal{E}} = (dx)_a^{n-1} \phi^a d_V\phi, \quad \sigma = (dx)_a^{n-1} d_V\phi^a d_V\phi$$

The Hamiltonian obtained from  $d\mathcal{H} - i_Q\sigma = 0$ :

$$\mathcal{H} = (dx)^n (\phi_a\phi^a - L|_{\mathcal{E}}) = \frac{1}{2}\phi^a\phi_a + V(\phi)$$

The intrinsic Lagrangian: *Schwinger*

$$\mathcal{L}^c = (dx)^n \left( \phi^a (\partial_a\phi - \frac{1}{2}\phi_a) - V(\phi) \right)$$

## Polywave equation

The simplest genuine higher derivative example is  $L = \frac{1}{2} \square \phi \square \phi = \frac{1}{2} \phi_{aa} \phi_{bb}$  (here and below  $\phi_{aa} = \eta^{ab} \phi_{ab}$ ). Presymplectic potential:

$$\chi = (-\phi_{acc} d_V \phi + \phi_{cc} d_V \phi_a) (dx)_a^{n-1}$$

Hamiltonian

$$\mathcal{H} = (dx)^n (-\phi_{acc} \phi_a + \frac{1}{2} \phi_{cc} \phi_{aa}).$$

The intrinsic action takes the form

$$S^C = \int d^n x (-\phi_{acc} (\partial_a \phi - \phi_a) + \phi_{cc} \partial_a \phi_a - \frac{1}{2} \phi_{aa} \phi_{cc}).$$

Note that the action depends on only the following variables  $\phi, \phi_a, \phi_{aa}, \phi_{acc}$  but NOT on the traceless component of  $\phi_{ab}$  and  $\phi_{abc}$ .

It is equivalent to  $\int \phi_{aa} \phi_{cc}$ . Indeed, varying  $\phi_a$  and  $\phi_{acc}$  gives  $\phi_a = \partial_a \phi$  and  $\phi_{acc} = \partial_a \phi_{cc}$  resulting in

$$\int d^n x (\phi_{cc} \partial_a \partial_a \phi - \frac{1}{2} \phi_{aa} \phi_{cc})$$

## YM theory

The YM field is  $A^a$  taking values in a Lie algebra  $\mathfrak{g}$  equipped with an invariant inner product  $\langle, \rangle$ . We will use notation  $A_{b_1 \dots b_l}^a$  for  $\partial_{b_1}^T \dots \partial_{b_l}^T A^a$ .

The Lagrangian:

$$L = \frac{1}{4} \langle F_{ab}, F_{ab} \rangle, \quad F_{ab} := A_a^b - A_b^a + [A^a, A^b].$$

Coordinates on  $\mathcal{E}$ :

$$x^a, A^a, F_{ab}, S_{ab} := A_a^b + A_b^a, A_{bc}^a, \dots$$

The one form  $\chi$  is given by

$$\chi = \frac{\partial L}{\partial A_a^b} dA^b (dx)_a^{n-1} = \langle F_{ab}, dA^b \rangle (dx)_a^{n-1}$$

The Hamiltonian

$$\mathcal{H} = \left( \frac{\partial L}{\partial A_a^b} A_a^b - \frac{1}{4} \langle F_{ab}, F_{ab} \rangle \right) (dx) = \frac{1}{2} \langle F_{ab}, \frac{1}{2} F_{ab} - [A^a, A^b] \rangle$$

The intrinsic action

$$\int \frac{1}{2} \langle F_{ab}, \partial_a A^b - \partial_b A^a \rangle - \frac{1}{2} \langle F_{ab}, \frac{1}{2} F_{ab} - [A^a, A^b] \rangle =$$
$$\int \frac{1}{2} \langle F_{ab}, \partial_a A^b - \partial_b A^a + [A^a, A^b] - \frac{1}{2} F_{ab} \rangle$$

equivalent to the starting point action through the elimination of  $F_{ab}$  by its own equations of motion.

Well-known first-order action for YM.

## Algebraic gauge symmetries

Assume that starting point Lagrangian  $\mathcal{L}$  does not have shift gauge symmetries i.e. there are no invertible nontrivial  $R_i^\alpha$  such that

$$R_\alpha^i[\phi, \partial_a^T] \frac{\delta^{EL} \mathcal{L}}{\delta \phi^i} = 0.$$

The intrinsic Lagrangian does have infinite amount of shift gauge symmetry. EOMs are

$$\sigma_{AB}(\mathbf{d}\psi^B - Q^B) = 0$$

so that any null vector of  $\sigma_{AB}$  gives rise to a shift gauge symmetry. If  $\sigma_{AB}R^B(\psi) = 0$  then  $\delta\psi^A = R^A\epsilon(x)$  is a gauge symmetry of the intrinsic action.

Interpretation of the intrinsic action: all its shift gauge symmetries are taken into account (the respective fields are set to fixed values – i.e. gauge-fixed).

Restrict to “reasonable theories: the Lagrangian theory is “reasonable” if by adding/eliminating auxiliary fields and local invertible change of variables the action  $\int \mathcal{L}$  can be brought to the form

$$S^{first} = \int \mathcal{L}^{first}[u] = \int d^d x (V_\lambda^a(u, x) \partial_a u^\lambda - H(u, x))$$

and such that its equations of motion do not imply algebraic constraints between undifferentiated fields  $u^\lambda$ . (i.e.  $u^\lambda$  reduced to  $\mathcal{E}$  remain independent)

Note that now frame-like Lagrangians are “reasonable”. Thanks to *Vasiliev, Zinovev, Alakalev, Shaynkman, Skvortsov, . . . . .* all known free Lagrangian HS fields are reasonable.

Proposition: for a “reasonable” system the original Lagrangian  $\mathcal{L}[\phi]$  and the intrinsic Lagrangian  $\mathcal{L}^C[\psi]$  are equivalent.

*Proof.* Equivalent Lagrangian formulations result in equivalent presymplectic structures on the equation manifold  $\mathcal{E}$ . It is enough to consider the first order Lagrangian. The respective presymplectic structure reads as

$$\chi = ((dx)_a^{n-1} V_\lambda^a du^\lambda)|_{\mathcal{E}} = (dx)_a^{n-1} V_\lambda^a du^\lambda$$

Hamiltonian:

$$\mathcal{H} = ((dx)^n V_\lambda^a u_a^\lambda - \mathcal{L}^{first})|_{\mathcal{E}} = (dx)^n H$$

Finally:

$$\mathcal{L}^C = (dx)^n (V_\lambda^a \partial_a u^\lambda - H(\phi))$$

and explicitly coincides with the starting point first order Lagrangian.  $\square$

## BRST extension and frame-like Lagrangians

To make our picture more geometrical let us introduce ghosts:

$$x^a, \psi^A \quad \rightarrow \quad x^a, \psi^A, C^\alpha$$

$$Q \equiv d_H \quad \rightarrow \quad Q = d_H + \gamma, \quad \gamma = C^\alpha R_\alpha^A(\psi) \frac{\partial}{\partial \psi^A} + C^\alpha C^\beta U_{\alpha\beta}^\gamma(\psi) \frac{\partial}{\partial C^\gamma}$$

$$d_H^2 = 0 = \gamma^2 \quad d_H \gamma + \gamma d_H = 0$$

Geometrically:  $\mathcal{E}$  is now equipped with two integrable distributions: Cartan ( $d_H$ ) and gauge ( $\gamma$ )



AKSZ sigma model with the target  $\mathcal{E}$

$$\psi^A \rightarrow \psi^A(x) \quad C^\alpha \rightarrow A_a^\alpha(x) dx^a$$

If  $\Psi^I = \{\psi^A, C^\alpha\}$ , equations of motion:

$$d\Psi^I = Q^I(\Psi) \rightarrow$$

$$dA^\alpha = d_H A^\alpha + U_{\alpha\beta}^\gamma(\psi) A^\gamma A^\beta, \quad d\psi^B = d_H \psi^B + R_\alpha^B(\Psi) A^\alpha$$

(Nonminimal) unfolded formulation

*Vasiliev*

Construction and equivalence proof

*Barnich, M.G., Semikhatov, Tipunin 2004, Barnich, M.G 2010*

## Example of gravity

After elimination of contractible pairs for  $Q$  the manifold  $\mathcal{E}$

$$e^a, \quad \omega^{ab}, \quad W_{ab}^{cd}, \quad W_{ab|e}^{cd}, \quad W_{ab|e\dots}^{cd}$$

– ghosts to which frame field and spin connection are associated and Weyl tensor and its covariant derivatives.

$$Qe^a = \omega^a_c e^c, \quad Q\omega^{ab} = \omega^a_c \omega^{cb} + e^c e^d W_{cd}^{ab}, \quad \dots,$$

Presymplectic potential  $\chi$  and form

*Alkalaev, M.G. 2013*

$$\chi = \frac{1}{2} \epsilon_{abcd} d\omega^{ab} e^c e^d, \quad \sigma = d\omega^{ab} de^c \epsilon_{abcd} e^d$$

Hamiltonian (term with Weyl tensor vanishes)

$$\mathcal{H} = Q^A \chi_A = \frac{1}{2} \omega^a_c \omega^{cb} \epsilon_{abcd} e^c e^d$$

Intrinsic action (frame-like GR action):

$$S^C = \int \chi_A (d\psi^A + Q^A) = S_{GR}[e, \omega] = \int (d\omega^{ab} + \omega^a_c \omega^{cb}) \epsilon_{abcd} e^c e^d$$

## Conclusions

- A Lagrangian system can be defined in terms of its equation manifold  $\mathcal{E}$  without referring to any particular realization of  $\mathcal{E}$  in one or another set of fields and choice of the Lagrangian. While the structure of the equation is encoded in the differential  $Q$  the Lagrangian is encoded in the compatible presymplectic structure  $\sigma$ .
- In particular, when looking for a Lagrangian for an equation  $\mathcal{E}$  it is enough to study compatible presymplectic structures on  $\mathcal{E}$ . No need to study possible explicit realizations of  $\mathcal{E}$ .
- Easy to see whether Lagrangian systems are equivalent or not.
- BRST extension to manifestly gauge systems. Intrinsic Lagrangian = Frame-like Lagrangian.
- The presymplectic form can be seen to originate from the odd symplectic form of the Batalin-Vilkovisky formalism.

## Parent Lagrangian

One way to understand where do the structure of the intrinsic Lagrangian comes from is to consider “parent” action for  $L = L(\phi, \phi_a, \phi_{ab})$ :

$$S^P = \int (L(\phi, \phi_a, \phi_{ab}) + \pi^a(\partial_a\phi - \phi_a) + \pi^{ac}(\partial_a\phi_c - \phi_{ac}) + \dots) .$$

Its equations of motion read as

$$\begin{aligned} \frac{\partial L}{\partial \phi} - \partial_a \pi^a &= 0, \\ \pi^a - \frac{\partial L}{\partial \phi_a} + \partial_c \pi^{ca} &= 0, & \pi^{ab} - \frac{\partial L}{\partial \phi_{ab}} &= 0, & \pi^{ab\dots} &= 0 \\ \phi_a &= \partial_a \phi, & \phi_{ab} &= \partial_{(a} \phi_{b)}, & \dots & \end{aligned}$$

Using the last line the derivatives in the first two lines can be replaced with the total derivatives. Using the second line the first equation becomes EL

$$\frac{\partial L}{\partial \phi} - \partial_a^T \frac{\partial L}{\partial \phi_a} + \partial_c^T \partial_a^T \frac{\partial L}{\partial \phi_{ca}} = 0 .$$

Introduce 1-form of degree  $n - 1$ :

$$\bar{\chi} = (dx)_a^{n-1} (\pi^a d\phi + \pi^{ab} d\phi_b + \dots)$$

"parent" Hamiltonian

$$\bar{\mathcal{H}} = (\pi^a \phi_a + \pi^{ab} \phi_{ab} + \dots - L(\phi, \phi_a, \phi_{ab}))(dx)^n.$$

The parent action can be written as

$$S^P = \int (\bar{\chi}_A d\Psi^A - \bar{\mathcal{H}}),$$

where  $\Psi^A$  stand for all the coordinates  $\phi, \phi_{\dots}, \pi^{\dots}$ .

Consider the following submanifold of the space of  $x^a, dx^a, \phi, \pi^{\dots}, \phi^{\dots}$

$$\pi^a - \frac{\partial L}{\partial \phi^a} + \partial_c^T \frac{\partial L}{\partial \phi_{ca}} = 0, \quad \pi^{ab} - \frac{\partial L}{\partial \phi_{ab}} = 0, \quad \pi^{ab\dots} = 0,$$

$$\partial_{a_1}^T \dots \partial_{a_k}^T (EL) = 0,$$

These are consequences of the parent action equations of motion.

The submanifold they single out is  $\mathcal{E}$  (equation manifold of  $L$ ).

$$\chi = \bar{\chi}|_{\mathcal{E}} \quad \text{Presymplectic potential for } L$$

One can show

$$i_Q d\sigma = d\mathcal{H}, \quad \mathcal{H} = \bar{\mathcal{H}}|_{\mathcal{E}}, \quad \sigma = d\chi$$

Furthermore,  $\chi$  and  $\mathcal{H}$  determine the intrinsic action

$$S^C[\psi] = \int \left( \chi_A(x, dx^a, \psi) d\psi^A - \mathcal{H}(x, dx^a, \psi) \right),$$

where  $x^a, \psi^A$  are coordinates on  $\mathcal{E}$ . This can be independently arrived at by eliminating auxiliary fields starting from the parent action.