

Partially massless spin 3 in the Fradkin-Vasiliev formalism

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Outlook

1 Kinematics

- Massless case
- Partially massless case

2 Gravitational interaction

- Massless case
- Minimal case
- Non-minimal case

Frame-like formalism for massless spin 3

- Frame-like Lagrangian for massless spin-3 in AdS_d :

$$\begin{aligned} \mathcal{L}_0 = & -\frac{1}{6} \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} [\Omega_\mu^{cd,a} \Omega_\nu^{cd,b} + 2\Omega_\mu^{ac,d} \Omega_\nu^{bc,d}] \\ & -\frac{2}{3} \left\{ \begin{matrix} \mu\nu\alpha \\ abc \end{matrix} \right\} \Omega_\mu^{ad,b} D_\nu \Phi_\alpha^{cd} + (d-1)\kappa \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} \Phi_\mu^{ac} \Phi_\nu^{bc} \end{aligned}$$

- It is invariant under the following gauge transformations:

$$\begin{aligned} \delta\Omega_\mu^{ab,c} &= D_\mu \eta^{ab,c} + \zeta^{ab,c}{}_\mu + \frac{(d-1)\kappa}{(d-2)} [2e_\mu^c \zeta^{ab} - e_\mu^{(a} \zeta^{b)c} - Tr] \\ \delta\Phi_\mu^{ab} &= D_\mu \zeta^{ab} + \eta^{ab}{}_\mu \end{aligned}$$

- We will need also an extra field (that do not enter the free Lagrangian):

$$\delta\Sigma_\mu^{ab,cd} = D_\mu \zeta^{ab,cd} + \kappa [\eta^{ab,(c} e_\mu^{d)} + \eta^{cd,(a} e_\mu^{b)} - Tr]$$

Gauge invariant objects and Lagrangian

- There are three gauge invariant two-forms:

$$\mathcal{R}_{\mu\nu}{}^{ab,cd} = D_{[\mu}\Sigma_{\nu]}{}^{ab,cd} - \kappa[\Omega_{[\mu}{}^{ab,(c}e_{\nu]}{}^{d)} + \Omega_{[\mu}{}^{cd,(a}e_{\nu]}{}^{b)} - \text{Tr}]$$

$$R_{\mu\nu}{}^{ab,c} = D_{[\mu}\Omega_{\nu]}{}^{ab,c} - \Sigma_{[\mu}{}^{ab,c}{}_{\nu]} + \frac{(d-1)\kappa}{(d-2)}[2e_{[\mu}{}^c\Phi_{\nu]}{}^{ab} + \dots]$$

$$\mathcal{T}_{\mu\nu}{}^{ab} = D_{[\mu}\Phi_{\nu]}{}^{ab} - \Omega_{[\mu}{}^{ab}{}_{\nu]}$$

- On-shell we have:

$$\mathcal{R}_{\mu\nu}{}^{ab,c} \approx 0, \quad \mathcal{T}_{\mu\nu}{}^{ab} \approx 0 \quad \Rightarrow \quad D_{[\mu}\mathcal{R}_{\nu\alpha]}{}^{ab,cd} \approx 0, \quad \mathcal{R}_{[\mu\nu}{}^{ab,c}{}_{\alpha]} \approx 0$$

- Free Lagrangian can be rewritten as follows:

$$\mathcal{L}_0 = \left\{ \begin{matrix} \mu\nu\alpha\beta \\ abcd \end{matrix} \right\} [a_1 \mathcal{R}_{\mu\nu}{}^{ae,bf} \mathcal{R}_{\alpha\beta}{}^{ce,df} + a_2 R_{\mu\nu}{}^{ae,b} R_{\alpha\beta}{}^{ce,d}]$$

$$a_1 \sim \frac{1}{\kappa^2}, \quad a_2 \sim \frac{1}{\kappa}$$

From massive to partially massless spin-3

- Massive spin-3 = massless spin-3,2,1,0

$$\left(\begin{array}{c} \Sigma_{\mu}{}^{ab,cd} \\ \Omega_{\mu}{}^{ab,c} \\ \Phi_{\mu}{}^{ab} \end{array} \right) \oplus \left(\begin{array}{c} W^{ab,cd} \\ \Omega_{\mu}{}^{a,b} \\ f_{\mu}{}^a \end{array} \right) \oplus \left(\begin{array}{c} F^{ab,c} \\ F^{a,b} \\ A_{\mu} \end{array} \right) \oplus \left(\begin{array}{c} \pi^{ab} \\ \pi^a \\ \varphi \end{array} \right)$$

- Partially massless spin-3 of depth one = massless spin-3,2

$$\left(\begin{array}{c} \Sigma_{\mu}{}^{ab,cd} \\ \Omega_{\mu}{}^{ab,c} \\ \Phi_{\mu}{}^{ab} \end{array} \right) \oplus \left(\begin{array}{c} W^{ab,cd} \\ \Omega_{\mu}{}^{ab} \\ f_{\mu}{}^a \end{array} \right)$$

Lagrangian and gauge transformations

$$\begin{aligned}
 \mathcal{L}_0 = & -\frac{1}{6} \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} [\Omega_\mu^{cd,a} \Omega_\nu^{cd,b} + 2\Omega_\mu^{ac,d} \Omega_\nu^{bc,d}] - \frac{2}{3} \left\{ \begin{matrix} \mu\nu\alpha \\ abc \end{matrix} \right\} \Omega_\mu^{ad,b} D_\nu \Phi_\alpha^c \\
 & + \frac{1}{2} \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} \Omega_\mu^{ac} \Omega_\nu^{bc} - \frac{1}{2} \left\{ \begin{matrix} \mu\nu\alpha \\ abc \end{matrix} \right\} \Omega_\mu^{ab} D_\nu f_\alpha^c \\
 & + m \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} [\Omega_\mu^{ac,b} f_\nu^c - \Omega_\mu^{ac} \Phi_\nu^{bc}] \\
 & + m^2 \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} \left[\frac{3(d-2)}{2d} \Phi_\mu^{ac} \Phi_\nu^{bc} - \frac{9(d-2)}{4(d-1)} f_\mu^a f_\nu^b \right], \quad m^2 = \frac{d\kappa}{3}
 \end{aligned}$$

$$\delta\Omega_\mu^{ab,c} = D_\mu \eta^{ab,c} + \frac{3m^2}{2d} [2e_\mu^c \xi^{ab} - e_\mu^{(a} \xi^{b)c} - Tr] - \frac{3m}{2d} [e_\mu^{(a} \eta^{b)c} - Tr]$$

$$\delta\Phi_\mu^{ab} = D_\mu \xi^{ab} + \eta^{ab}{}_\mu + \frac{3m}{2(d-1)} [e_\mu^{(a} \xi^{b)} - \frac{2}{d} g^{ab} \xi_\mu]$$

$$\delta\Omega_\mu^{ab} = D_\mu \eta^{ab} - m\eta_\mu^{[a,b]} + \frac{9m^2}{2(d-1)} e_\mu^{[a} \xi^{b]}$$

$$\delta f_\mu^a = D_\mu \xi^a + \eta_\mu^a + m\xi_\mu^a$$

Gauge invariant objects

- Correspondingly, we have six gauge invariant objects:

$$\mathcal{R}_{\mu\nu}{}^{ab,cd} = D_{[\mu}\Sigma_{\nu]}{}^{ab,cd} - \frac{3m}{2d}[W^{ab,(c}{}_{[\mu}e_{\nu]}{}^{d)} + W^{cd,(a}{}_{[\mu}e_{\nu]}{}^{b)}]$$

$$\mathcal{R}_{\mu\nu}{}^{ab,c} = D_{[\mu}\Omega_{\nu]}{}^{ab,c} - \Sigma_{[\mu}{}^{ab,c}{}_{\nu]} - \frac{3m}{2d}[e_{[\mu}{}^{(a}\Omega_{\nu]}{}^{b)c} - Tr] + \dots$$

$$\mathcal{T}_{\mu\nu}{}^{ab} = D_{[\mu}\Phi_{\nu]}{}^{ab} - \Omega_{[\mu}{}^{ab}{}_{\nu]} + \frac{3m}{2(d-1)}[e_{[\mu}{}^{(a}f_{\nu]}{}^{b)} + \frac{2}{d}g^{ab}f_{[\mu,\nu]}]$$

$$\mathcal{W}_{\mu}{}^{ab,cd} = D_{\mu}W^{ab,cd} - 2m\Sigma_{\mu}{}^{ab,cd}$$

$$\mathcal{R}_{\mu\nu}{}^{ab} = D_{[\mu}\Omega_{\nu]}{}^{ab} + m\Omega_{[\mu,\nu]}{}^{[a,b]} + \frac{9m^2}{2(d-1)}e_{[\mu}{}^{[a}f_{\nu]}{}^{b]} + W_{[\mu}{}^{a,b}{}_{\nu]}$$

$$\mathcal{T}_{\mu\nu}{}^a = D_{[\mu}f_{\nu]}{}^a - \Omega_{[\mu,\nu]}{}^a - m\Phi_{[\mu,\nu]}{}^a$$

- On-shell:

$$\mathcal{R}_{\mu\nu}{}^{ab,c} \approx 0, \quad \mathcal{T}_{\mu\nu}{}^{ab} \approx 0, \quad \mathcal{R}_{\mu\nu}{}^{a,b} \approx 0, \quad \mathcal{T}_{\mu\nu}{}^a \approx 0$$

Skvortsov-Vasiliev version

- We have four one-forms only:

$$(\Omega_\mu{}^{ab,c}, \Phi_\mu{}^{ab}) \oplus (\Omega_\mu{}^{ab}, f_\mu{}^a)$$

- and four gauge invariant two-forms:

$$\mathcal{R}_{\mu\nu}{}^{ab,c} = D_{[\mu}\Omega_{\nu]}{}^{ab,c} - \frac{3m}{2d}[e_{[\mu}{}^{(a}\Omega_{\nu]}{}^{b)c} - Tr] + \frac{3m^2}{2d}[2e_{[\mu}{}^c\Phi_{\nu]}{}^{ab} + \dots]$$

$$\mathcal{T}_{\mu\nu}{}^{ab} = D_{[\mu}\Phi_{\nu]}{}^{ab} - \Omega_{[\mu}{}^{ab}{}_{\nu]} + \frac{3m}{2(d-1)}[e_{[\mu}{}^{(a}f_{\nu]}{}^{b)} + \frac{2}{d}g^{ab}f_{[\mu,\nu]}]$$

$$R_{\mu\nu}{}^{ab} = D_{[\mu}\Omega_{\nu]}{}^{ab} + m\Omega_{[\mu,\nu]}{}^{[a,b]} + \frac{9m^2}{2(d-1)}e_{[\mu}{}^{[a}f_{\nu]}{}^{b]}$$

$$\mathcal{T}_{\mu\nu}{}^a = D_{[\mu}f_{\nu]}{}^a - \Omega_{[\mu,\nu]}{}^a - m\Phi_{[\mu,\nu]}{}^a$$

- Free Lagrangian can be written as:

$$\mathcal{L}_0 = \left\{ \begin{matrix} \mu\nu\alpha\beta \\ abcd \end{matrix} \right\} [a_2 \mathcal{R}_{\mu\nu}{}^{ae,b} \mathcal{R}_{\alpha\beta}{}^{ce,d} + a_3 \mathcal{R}_{\mu\nu}{}^{ab} \mathcal{R}_{\alpha\beta}{}^{cd}]$$

What we can expect for 3-3-2 vertices

- Massless spin-3 \oplus massless spin-2

$$N = 4, 6(, 8)$$

- Partially massless spin-3 \oplus massless spin-2
(Joung, Lopez, Taronna 12)

$$N = 2, 4, 4, 6, 6$$

- Massive spin-3 \oplus massless spin-2 (Metsaev 06, 12)

$$N = 3, 4, 4, 5, 5, 6, 6(, 7, 8)$$

Deformations of curvatures

- We have to consider the most general quadratic deformations for all curvatures and require that the deformed curvatures transform covariantly.
- For spin 3 curvatures they correspond to the minimal substitution rules. Variations that do not vanish on-shell:

$$\begin{aligned} \delta \hat{\mathcal{R}}_{\mu\nu}{}^{ab,cd} &\approx c_0 [R_{\mu\nu}{}^{e(a}\zeta^b)e,cd + R_{\mu\nu}{}^{e(c}\zeta^d)e,ab \\ &\quad - \hat{\eta}^{e(a}\mathcal{R}_{\mu\nu}{}^{b)e,cd} - \hat{\eta}^{e(c}\mathcal{R}_{\mu\nu}{}^{d)e,ab}] \\ \delta \hat{\mathcal{R}}_{\mu\nu}{}^{ab,c} &\approx c_0 [R_{\mu\nu}{}^{d(a}\eta^b)d,c + R_{\mu\nu}{}^{dc}\eta^{ab,d} + \mathcal{R}_{\mu\nu}{}^{ab,cd}\hat{\xi}^d] \end{aligned}$$

- For the gravitational curvature we obtain:

$$\delta \hat{R}_{\mu\nu}{}^{ab} \approx b_1 \mathcal{R}_{\mu\nu}{}^{de,c[a}\zeta^b]c,de$$

Interacting Lagrangian

- is the sum of the free Lagrangians where curvatures are replaced by the deformed ones plus abelian vertex:

$$\mathcal{L} = \left\{ \begin{matrix} \mu\nu\alpha\beta \\ abcd \end{matrix} \right\} [a_1 \hat{\mathcal{R}}_{\mu\nu}{}^{ae,bf} \hat{\mathcal{R}}_{\alpha\beta}{}^{ce,df} + a_2 \hat{\mathcal{R}}_{\mu\nu}{}^{ae,b} \hat{\mathcal{R}}_{\alpha\beta}{}^{cw,d} + a_0 \hat{R}_{\mu\nu}{}^{ab} \hat{R}_{\alpha\beta}{}^{cd}] \\ + c_1 \left\{ \begin{matrix} \mu\nu\alpha\beta\gamma \\ abcde \end{matrix} \right\} \mathcal{R}_{\mu\nu}{}^{af,bg} \mathcal{R}_{\alpha\beta}{}^{cf,dg} h_{\gamma}{}^e$$

- Invariance fixes the relation

$$b_1 \Lambda \sim c_0$$

- Both non-abelian and abelian vertices contain terms up to six derivatives but we can adjust coefficients so that all six derivatives terms vanish on-shell (Vasiliev 11).

Deformations of curvatures

- We have one-forms only \Rightarrow the procedure goes exactly as in the massless case.
- For the partially massless spin-3 it again corresponds to the minimal substitution rules. Transformations that do not vanish on-shell look like:

$$\begin{aligned}\delta \hat{\mathcal{R}}_{\mu\nu}{}^{ab,c} &\approx c_0 [R_{\mu\nu}{}^{d(a}\eta^{b)d,c} + R_{\mu\nu}{}^{dc}\eta^{ab,d}] \\ \delta \hat{\mathcal{R}}_{\mu\nu}{}^{ab} &\approx -R_{\mu\nu}{}^{c[a}\eta^{b]c} - m\mathcal{R}_{\mu\nu}{}^{c[a,b]\hat{\xi}^c]}\end{aligned}$$

- For the gravitational curvature we obtain:

$$\delta \hat{R}_{\mu\nu}{}^{ab} \approx b_0 \mathcal{R}_{\mu\nu}{}^{cd,[a}\eta^{cd,|b]} + 2b_0 \mathcal{R}_{\mu\nu}{}^{[a|c,d}\eta^{b]c,d}$$

Interacting Lagrangian

- has the same structure:

$$\mathcal{L} = \left\{ \begin{matrix} \mu\nu\alpha\beta \\ abcd \end{matrix} \right\} [a_2 \hat{\mathcal{R}}_{\mu\nu}{}^{ae,b} \hat{\mathcal{R}}_{\alpha\beta}{}^{ce,d} + a_3 \hat{\mathcal{R}}_{\mu\nu}{}^{ab} \hat{\mathcal{R}}_{\alpha\beta}{}^{cd} + a_0 \hat{R}_{\mu\nu}{}^{ab} \hat{R}_{\alpha\beta}{}^{cd}] \\ + c_1 \left\{ \begin{matrix} \mu\nu\alpha\beta\gamma \\ abcde \end{matrix} \right\} \mathcal{R}_{\mu\nu}{}^{af,b} \mathcal{R}_{\alpha\beta}{}^{cf,d} h_\gamma{}^e$$

- Invariance fixes relation between two coupling constants:

$$c_0 \sim b_0$$

- Both non-abelian and abelian vertices contain terms with up to four derivatives.

Deformations of curvatures

- For the partially massless curvatures we again get minimal substitutions:

$$\delta \hat{\mathcal{R}}_{\mu\nu}{}^{ab,cd} \approx R_{\mu\nu}{}^{e(a}\zeta^{b)e,cd} + R_{\mu\nu}{}^{e(c}\zeta^{d)e,ab} - \frac{3m}{2d} [\hat{\xi}^{(a}\mathcal{W}_{[\mu,\nu]}{}^{b),cd} + \dots$$

$$\delta \hat{\mathcal{R}}_{\mu\nu}{}^{ab,c} \approx R_{\mu\nu}{}^{d(a}\eta^{b)d,c} + R_{\mu\nu}{}^{dc}\eta^{ab,d} - \mathcal{R}_{\mu\nu}{}^{ab,cd}\hat{\xi}^d$$

- The most general solution for the gravitational curvature and torsion we get six free parameters:

$$b_0, b_1, b_2, b_3, b_4, b_5$$

- At the same time we have five possible field redefinitions:

$$\omega_{\mu}{}^{ab} \Rightarrow \omega_{\mu}{}^{ab} + \kappa_1 \sum_{\mu}{}^{de,c[a} W^{b]c,de} + \kappa_2 W^{ac,bd} \Omega_{\mu}{}^{cd}$$

$$h_{\mu}{}^a \Rightarrow h_{\mu}{}^a + \kappa_3 W^{ab,cd} \Omega_{\mu}{}^{cd,b} + \kappa_4 W^{ab,cd} W_{\mu}{}^{b,cd} + \kappa_5 e_{\mu}{}^a W^2$$

Interacting Lagrangian

- has the same general structure:

$$\begin{aligned}
 \mathcal{L} = & \left\{ \begin{matrix} \mu\nu\alpha\beta \\ abcd \end{matrix} \right\} [a_1 \hat{\mathcal{R}}_{\mu\nu}{}^{ae,bf} \hat{\mathcal{R}}_{\alpha\beta}{}^{ce,df} + a_2 \hat{\mathcal{R}}_{\mu\nu}{}^{ae,b} \hat{\mathcal{R}}_{\alpha\beta}{}^{ce,d} + a_3 \hat{\mathcal{R}}_{\mu\nu}{}^{ab} \hat{\mathcal{R}}_{\alpha\beta}{}^{cd}] \\
 & + a_4 \left\{ \begin{matrix} \mu\nu\alpha \\ abc \end{matrix} \right\} \hat{\mathcal{R}}_{\mu\nu}{}^{ad,e} \hat{\mathcal{W}}_{\alpha}{}^{bd,ce} + a_5 \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} \hat{\mathcal{W}}_{\mu}{}^{ac,de} \hat{\mathcal{W}}_{\nu}{}^{bc,de} \\
 & + a_0 \left\{ \begin{matrix} \mu\nu\alpha\beta \\ abcd \end{matrix} \right\} \hat{\mathcal{R}}_{\mu\nu}{}^{ab} \hat{\mathcal{R}}_{\alpha\beta}{}^{cd} \\
 & + c_1 \left\{ \begin{matrix} \mu\nu\alpha\beta\gamma \\ abcde \end{matrix} \right\} \mathcal{R}_{\mu\nu}{}^{af,bg} \mathcal{R}_{\alpha\beta}{}^{cf,dg} h_{\gamma}{}^e + c_2 \left\{ \begin{matrix} \mu\nu\alpha \\ abc \end{matrix} \right\} \mathcal{W}_{\mu}{}^{ad,ef} \mathcal{W}_{\nu}{}^{bd,ef} h_{\alpha}{}^c
 \end{aligned}$$

- The number of independent vertices depends on which field redefinitions are considered as admissible.

Final remarks

- In the Skvortsov-Vasiliev case to reproduce vertices with more than four derivatives we still have to include some zero-forms.
- If we consider the general massive case and take partially massless limit we naturally end with the non-minimal version.
- The general formalism can be applied to the massive case. From one hand the most general deformations produce a lot of higher derivatives vertices for lower spin components. From the other hand we will face a lot of possible field redefinitions.
- Technically the most important open question is the admissibility of these redefinitions.